

Timeless formulation of Wigner's friend scenarios

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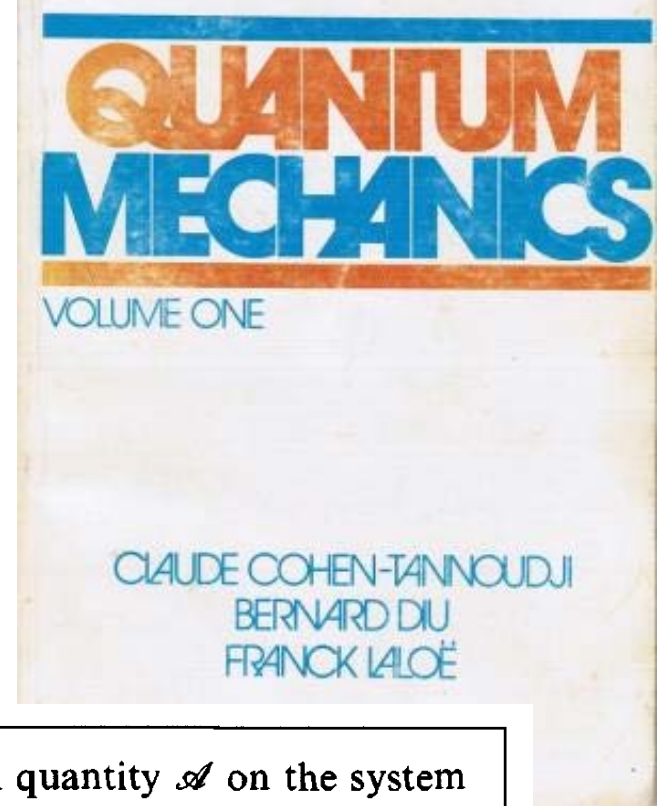
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Outlook

- The quantum measurement problem
- Wigner's friend gedanken experiment
- Page-Wootters timeless formalism
- Conditional probabilities in Wigner's friend scenarios
- What is the “true” quantum state? Is the collapse of the wave function absolute or relative?

The postulates of quantum mechanics

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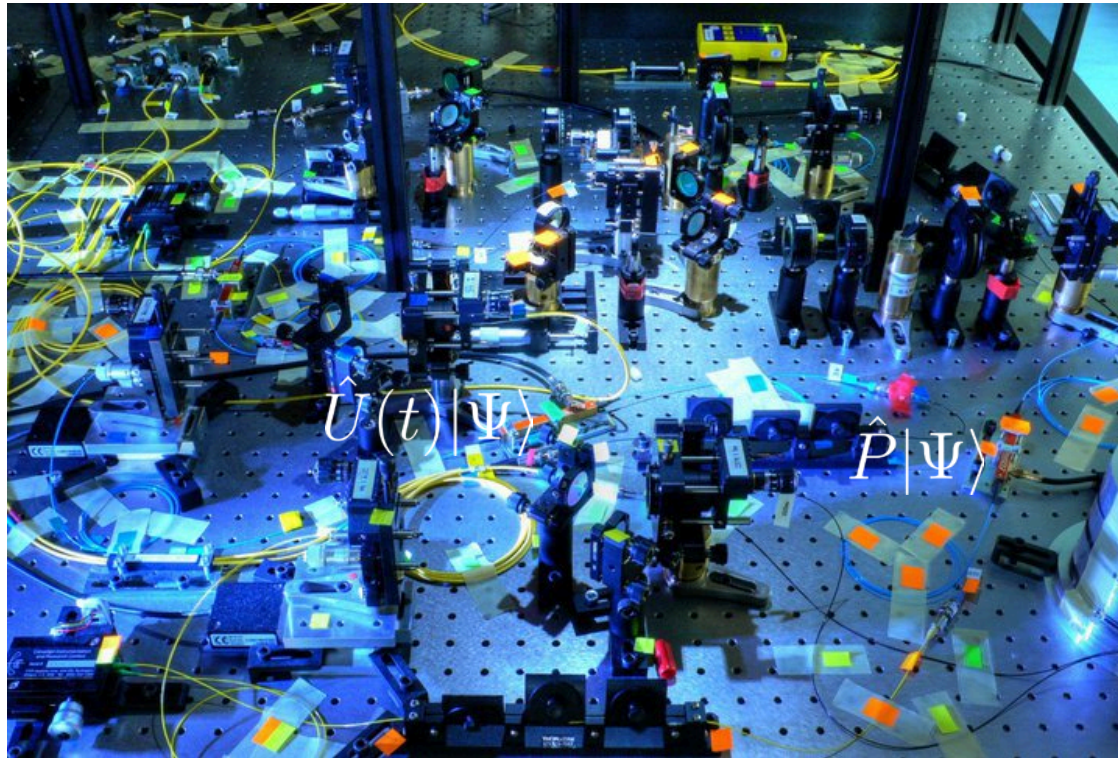
Fifth Postulate: If the measurement of the physical quantity \mathcal{A} on the system in the state $|\psi\rangle$ gives the result a_n , the state of the system immediately after the measurement is the normalized projection, $\frac{P_n |\psi\rangle}{\sqrt{\langle \psi | P_n | \psi \rangle}}$, of $|\psi\rangle$ onto the eigensubspace associated with a_n .

Sixth Postulate: The time evolution of the state vector $|\psi(t)\rangle$ is governed by the Schrödinger equation:

$$i\hbar \frac{d}{dt} |\psi(t)\rangle = H(t) |\psi(t)\rangle$$

where $H(t)$ is the observable associated with the total energy of the system.

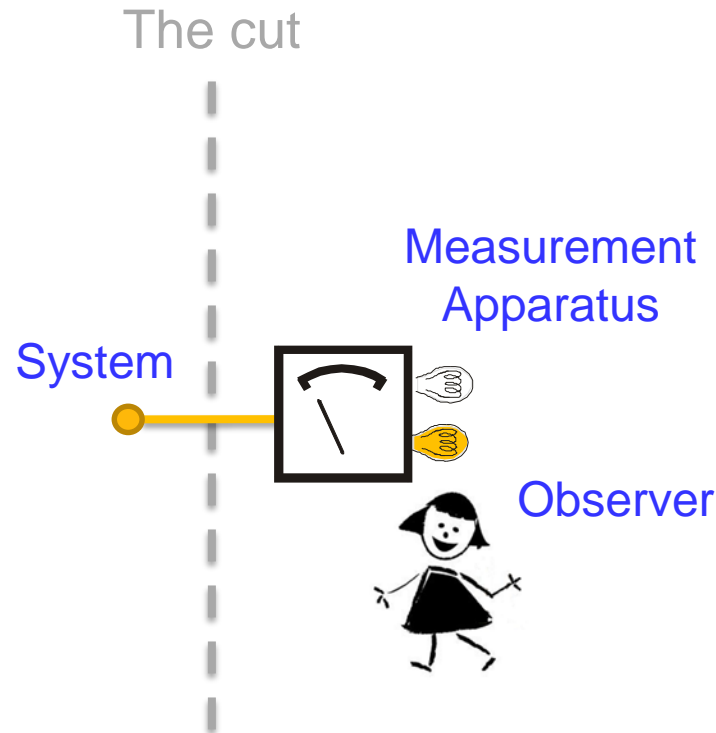
The quantum measurement problem



What makes a measurement a measurement? When to choose to apply unitary evolution and when the projection rule?

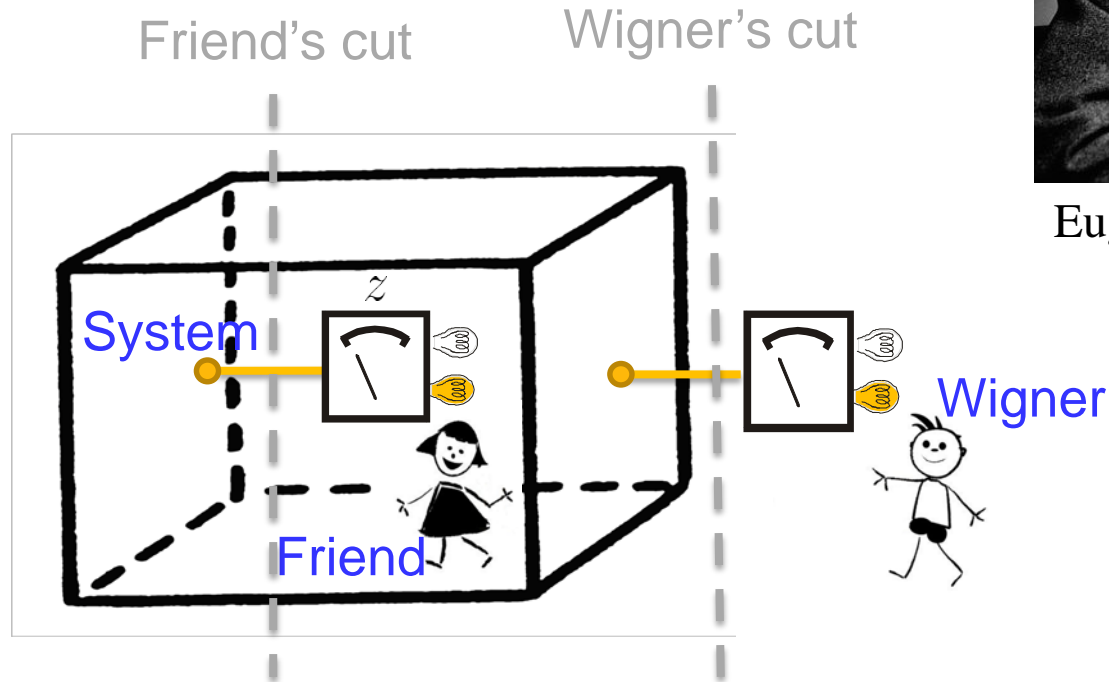
(Presumably, manufacturers of photo-diodes know the answer.)

The “cut”



The „cut“ as a *functional* distinction between object and subject, not a physical one between „microworld“ and „macroworld“.

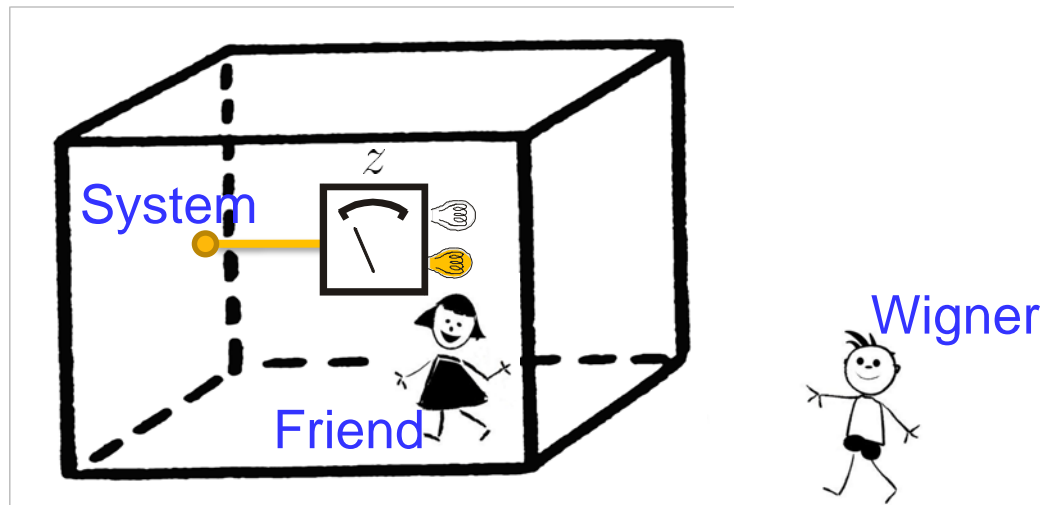
The “cut”



In moving the “cut”, the F’s measurement instrument loses its function and becomes itself a quantum system – an object that can be observed by a further set of W’s measurement instruments.

Wigner's friend thought experiment

While F performs a measurement on the system and subsequently applies the state-update rule, W describes the entire process unitarily.



Wigner: $|\psi(0)\rangle = 1/\sqrt{2}(|\uparrow\rangle_S + |\downarrow\rangle_S)|R\rangle_F$
 $|\psi(t)\rangle = 1/\sqrt{2}(|\uparrow\rangle_S|\uparrow\rangle_F + |\downarrow\rangle_S|\downarrow\rangle_F)$

Friend: Either $|\uparrow\rangle_S$ or $|\downarrow\rangle_S$

All degrees of freedom that get coupled with the outcomes (apparatus, friend's memory, etc.)

What is the “true” quantum state?

There is nothing wrong with W and F assigning different quantum states to their respective experimental situations.

The probabilities are to be understood as **relational in the sense that their determinacy is relative to an observer** (*no-go theorem for “observation-independent facts”*).

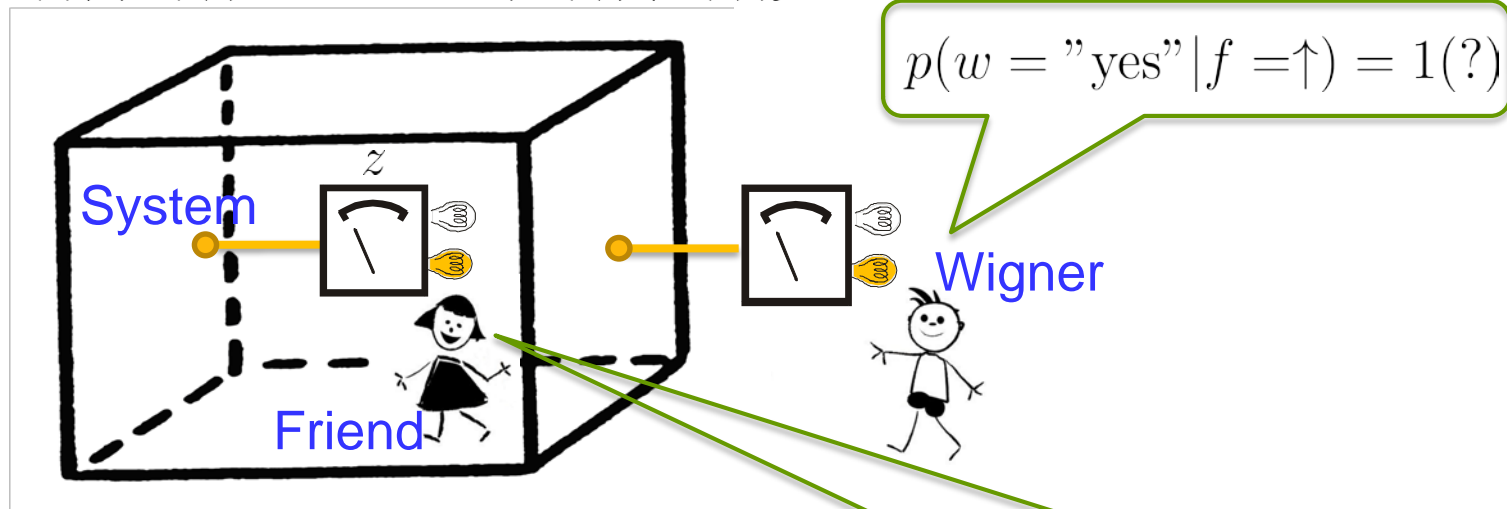
(*Rovelli’s relational interpretation, QBism, Neo-Copenhagen interpretation, Many-worlds etc.*)

Can we think of an experimental situation in which W or F might get an evidence that their state assignment is “incomplete”?

F's prediction about W's measurement

W verifies his state assignment by performing the measurement:

$$\{ \text{"yes"}: |\psi(t)\rangle\langle\psi(t)|, \text{"no"}: \mathbb{1} - |\psi(t)\rangle\langle\psi(t)| \}$$



$$|\psi(t)\rangle = 1/\sqrt{2}(|\uparrow\rangle_S |\uparrow\rangle_F + |\downarrow\rangle_S |\downarrow\rangle_F)$$

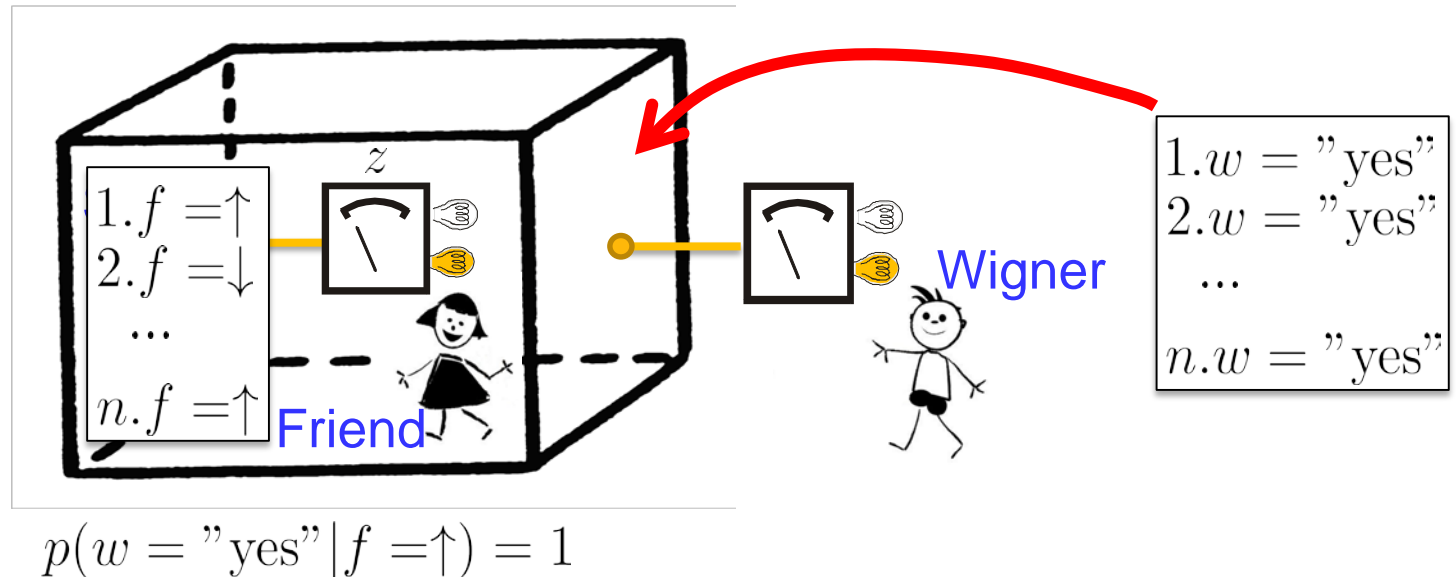
$$p(w = \text{"yes"} | f = \uparrow) = ?$$

1. QM makes no predictions for measurements on the observer (?)
2. $p(w = \text{"yes"} | f = \uparrow) = 1/2$ (?)
3. $p(w = \text{"yes"} | f = \uparrow) = 1$ (?)

F's prediction about W's measurement

W verifies his state assignment by performing the measurement:

$$\{ \text{"yes"}: |\psi(t)\rangle\langle\psi(t)|, \text{"no"}: \mathbb{1} - |\psi(t)\rangle\langle\psi(t)| \}$$



The state is an eigenstate of the measurement operator, and hence the measurement can be performed repeatedly without „disturbing“ it.

It seems that sometimes F's should adopt W's quantum state assignment to make her predictions.

When to use one or the other state? Is there a quantum formalism that would enable F (and W) to compute conditional probabilities in a general situation?

Page-Wootters timeless formalism

In 1983 Don Page and William Wootters (PW) suggested a formalism to address the “problem of time”. The Hamiltonian constraint:

$$\hat{H}|\Psi\rangle\rangle = 0 \Rightarrow i\hbar \frac{d|\Psi\rangle\rangle}{dt} = \hat{H}|\Psi\rangle\rangle = 0$$

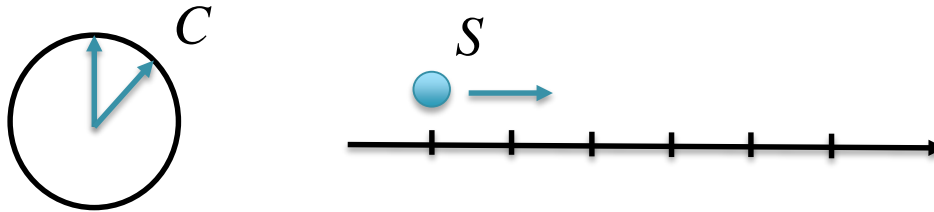
PW formalism assigns one **timeless state** from which probabilities can be computed, without the need to evolve quantum states at and in-between measurements.

Idea: Apply it to Wigner’s friend scenarios to overcome the dichotomy between the unitary evolution and the state-update rule.

Page-Wootters timeless formalism

The Hamiltonian constraint:

$$\hat{H}|\Psi\rangle\rangle = \left(\hat{H}_C + \hat{H}_S\right) |\Psi\rangle\rangle = 0$$



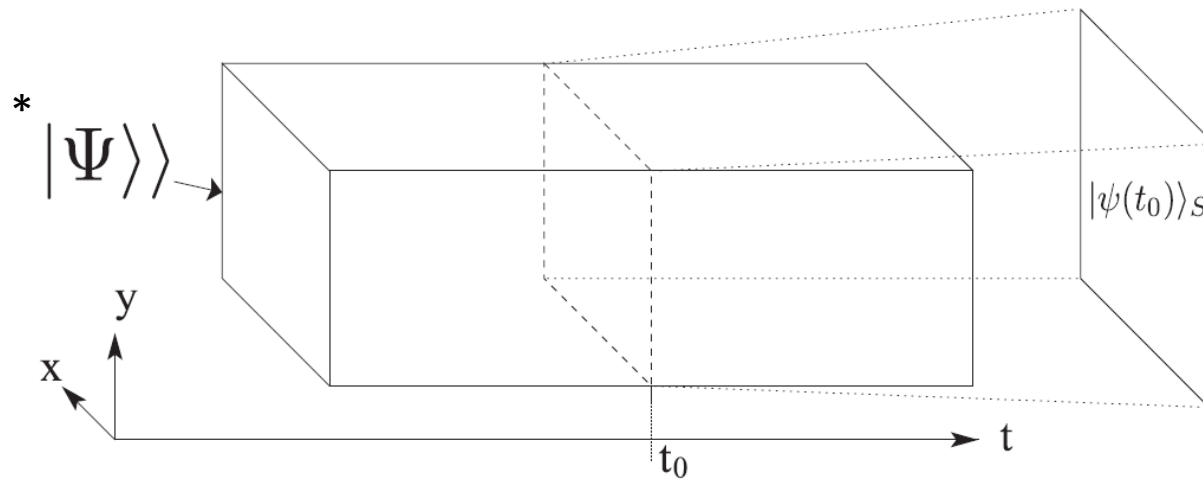
Kinematical Hilbert space: $|\psi\rangle \in \mathcal{H}_C \otimes \mathcal{H}_S$

Physical Hilbert space: $|\Psi\rangle\rangle = P^{\text{ph}}|\psi\rangle \in \mathcal{H}$, $P^{\text{ph}} := \int_{\mathbb{R}} ds e^{-is\hat{H}}$

Clock state indicating time t

$$|t'\rangle = e^{-i\hat{H}_C(t'-t)}|t\rangle, \quad \langle t'|t\rangle = \delta(t' - t), \quad \mathbb{1}_C = \int dt |t\rangle\langle t|$$

Timeless quantum state

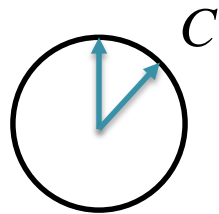


$$|\Psi\rangle\rangle = \left(\int_{\mathbb{R}} |t\rangle\langle t| \right) \otimes \mathbb{1}_S |\Psi\rangle\rangle = \int_{\mathbb{R}} dt |t\rangle |\psi_S(t)\rangle$$

Superposition of „histories“

Time is what a clock reads

„The state of the system at the time t “ is the joint state $|\Psi\rangle\rangle$ of the clock and the system, condition on the clock being in state $|t\rangle$.



$$|\psi_S(t)\rangle := (\langle t| \otimes \mathbb{1}_S) |\Psi\rangle\rangle.$$

The state satisfies the Schrödinger equation: $i \frac{d}{dt} |\psi_S(t)\rangle = \hat{H}_S |\psi_S(t)\rangle$

Born's rule

The single-time probability:

$$P(m \text{ when } t) = \frac{\langle\langle\Psi|(|t\rangle\langle t| \otimes \Pi_m)|\Psi\rangle\rangle}{\langle\langle\Psi|(|t\rangle\langle t| \otimes \mathbb{1}_S)|\Psi\rangle\rangle}$$

Measurement operator
 $\hat{M} = \sum_m m \Pi_m$

A problem with **the conditional probability** (Kuchar's criticism):

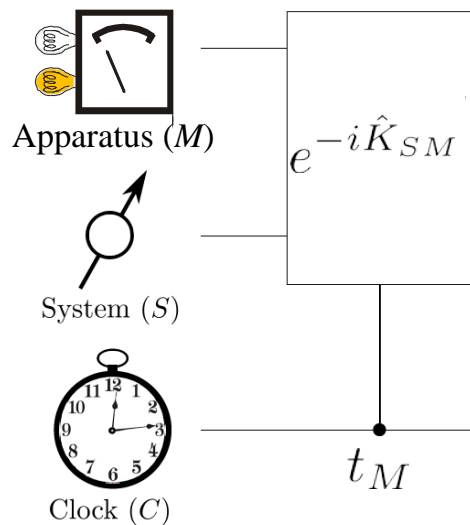
$$\begin{aligned} &P(m \text{ when } t_2 | n \text{ when } t_1) \\ &= \frac{P(m \text{ when } t_2 \text{ \& } n \text{ when } t_1)}{P(n \text{ when } t_1)} \\ &= \frac{\langle\langle\Psi|(|t_1\rangle\langle t_1| \otimes \Pi_n)(|t_2\rangle\langle t_2| \otimes \Pi_m)(|t_1\rangle\langle t_1| \otimes \Pi_n)|\Psi\rangle\rangle}{\langle\langle\Psi|(|t_1\rangle\langle t_1| \otimes \Pi_n)|\Psi\rangle\rangle} \\ &= \delta^2(t_2 - t_1) |\langle m | n \rangle|^2 \neq |\langle m | U(t_2 - t_1) | n \rangle|^2 \end{aligned}$$

Overcoming the problem

Including the interaction with the measurement apparatus in the Hamiltonian constraint

$$\hat{H}|\Psi\rangle\rangle = \left(\hat{H}_C + \hat{H}_S + \delta(\hat{T} - t_M) \hat{K}_{SM} \right) |\Psi\rangle\rangle = 0$$

$$e^{-i\hat{K}_{SM}}|\psi_S\rangle|R_M\rangle = \sum_m \Pi_m |\psi_S\rangle|m_M\rangle$$



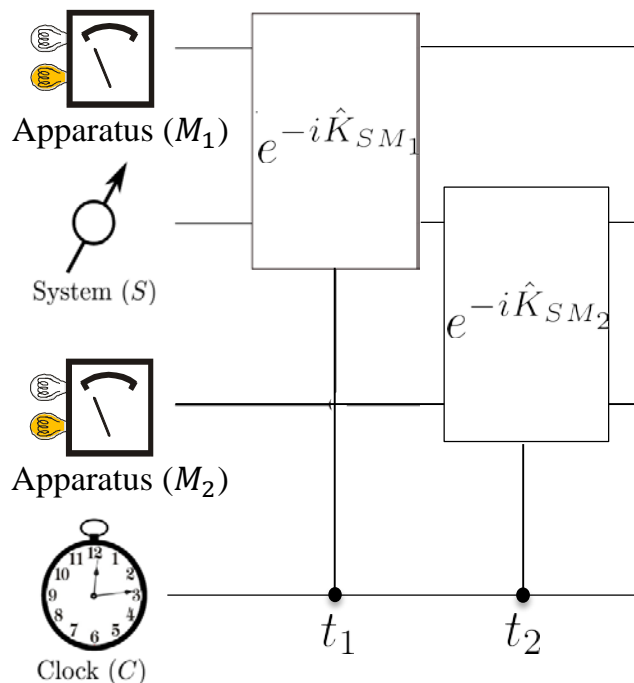
$$|\Psi\rangle\rangle = \int_{-\infty}^{t_M} dt |t\rangle |\psi_S\rangle |R_M\rangle + \int_{t_M}^{\infty} dt |t\rangle \sum_m \Pi_m |\psi_S\rangle |m_M\rangle$$

$$P(m \text{ when } t) = \frac{\langle\langle\Psi|(|t\rangle\langle t| \otimes \mathbb{1}_S \otimes \Pi^m)|\Psi\rangle\rangle}{\langle\langle\Psi|(|t\rangle\langle t| \otimes \mathbb{1}_{SM})|\Psi\rangle\rangle}$$

Overcoming the problem

Including the interaction with the measurement apparatuses in the Hamiltonian constraint

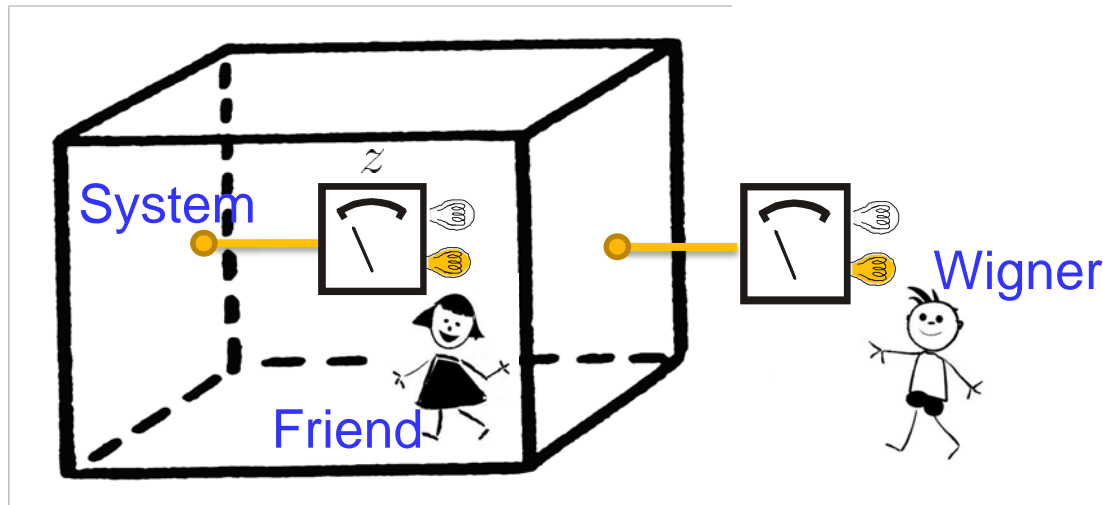
$$\hat{H}|\Psi\rangle\rangle = \left(\hat{H}_C + \hat{H}_S + \delta(\hat{T} - t_1)\hat{K}_{SM_1} + \delta(\hat{T} - t_2)\hat{K}_{SM_2} \right) |\Psi\rangle\rangle = 0$$



$$\begin{aligned} |\Psi\rangle\rangle &= \int_{-\infty}^{t_1} dt |t\rangle |\psi_S\rangle |R_{M_1}\rangle |R_{M_2}\rangle \\ &+ \int_{t_1}^{t_2} dt |t\rangle \sum_m \Pi_m |\psi_S\rangle |m_{M_1}\rangle |R_{M_2}\rangle \\ &+ \int_{t_2}^{\infty} dt |t\rangle \sum_{n,m} \Pi_n \Pi_m |\psi_S\rangle |m_{M_1}\rangle |n_{M_2}\rangle \end{aligned}$$

$$\begin{aligned} P(n \text{ when } t_2 | m \text{ when } t_1) &= \frac{\langle\langle \Psi | (|t_2\rangle\langle t_2| \otimes \mathbb{1}_S \otimes \Pi^m \otimes \Pi^n) | \Psi \rangle\rangle}{\langle\langle \Psi | (|t_1\rangle\langle t_1| \otimes \mathbb{1}_S \otimes \Pi^m \otimes \mathbb{1}_{M_2}) | \Psi \rangle\rangle} \end{aligned}$$

Wigner's friend situation



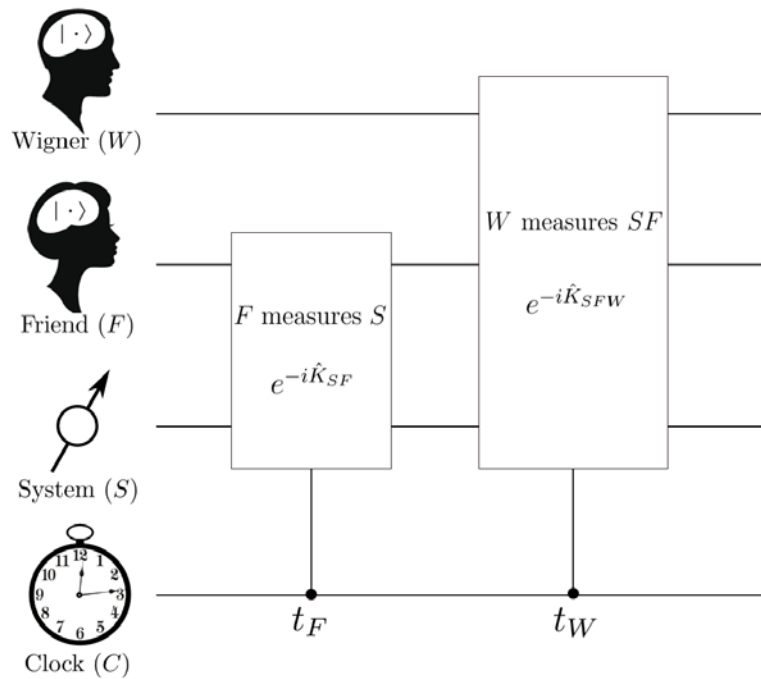
Initial state: $|\psi_S\rangle = a|\uparrow_S\rangle + b|\downarrow_S\rangle$, $a, b \in \mathbb{R}$

The friend measures the spin along z

Wigner measures $\Pi_{yes} = |\text{yes}\rangle\langle\text{yes}|$ and $\Pi_{no} = \mathbb{1} - |\text{yes}\rangle\langle\text{yes}|$
 $|\text{yes}_{SF}\rangle = \alpha|\uparrow_S\rangle|\uparrow_F\rangle + \beta|\downarrow_S\rangle|\downarrow_F\rangle, \alpha, \beta \in \mathbb{R}$

Wigner's friend situation

$$\hat{H}|\Psi\rangle\rangle = \left(\hat{H}_C + \hat{H}_S + \delta(\hat{T} - t_F)\hat{K}_{SF} + \delta(\hat{T} - t_W)\hat{K}_{SFW} \right) |\Psi\rangle\rangle = 0$$



$$\begin{aligned} |\Psi\rangle\rangle &= \int_{-\infty}^{t_F} dt |t\rangle |\psi_S\rangle |R_F\rangle |R_W\rangle \\ &+ \int_{t_F}^{t_W} dt |t\rangle \sum_{f \in \{\uparrow, \downarrow\}} \Pi_f |\psi_S\rangle |f_F\rangle |R_W\rangle \\ &+ \int_{t_W}^{\infty} dt |t\rangle \sum_{\substack{f \in \{\uparrow, \downarrow\} \\ w \in \{\text{yes}, \text{no}\}}} \Pi_w \Pi_f |\psi_S\rangle |f_F\rangle |w_W\rangle \end{aligned}$$

“Collapse” conditional probability

Definition:

Applied s.t. the state still satisfies the constraint
(Dolby, gr-qc/0406034)

$$P_1(n \text{ when } t_2 | m \text{ when } t_1) = \frac{\langle \langle \Psi | | t_1 \rangle \langle t_1 | \otimes \Pi^m P^{\text{ph}}(|t_2\rangle \langle t_2| \otimes \Pi^n) P^{\text{ph}} | t_1 \rangle \langle t_1 | \otimes \Pi^m | \Psi \rangle \rangle}{\langle \langle \Psi | | t_1 \rangle \langle t_1 | \otimes \Pi^m | \Psi \rangle \rangle}$$

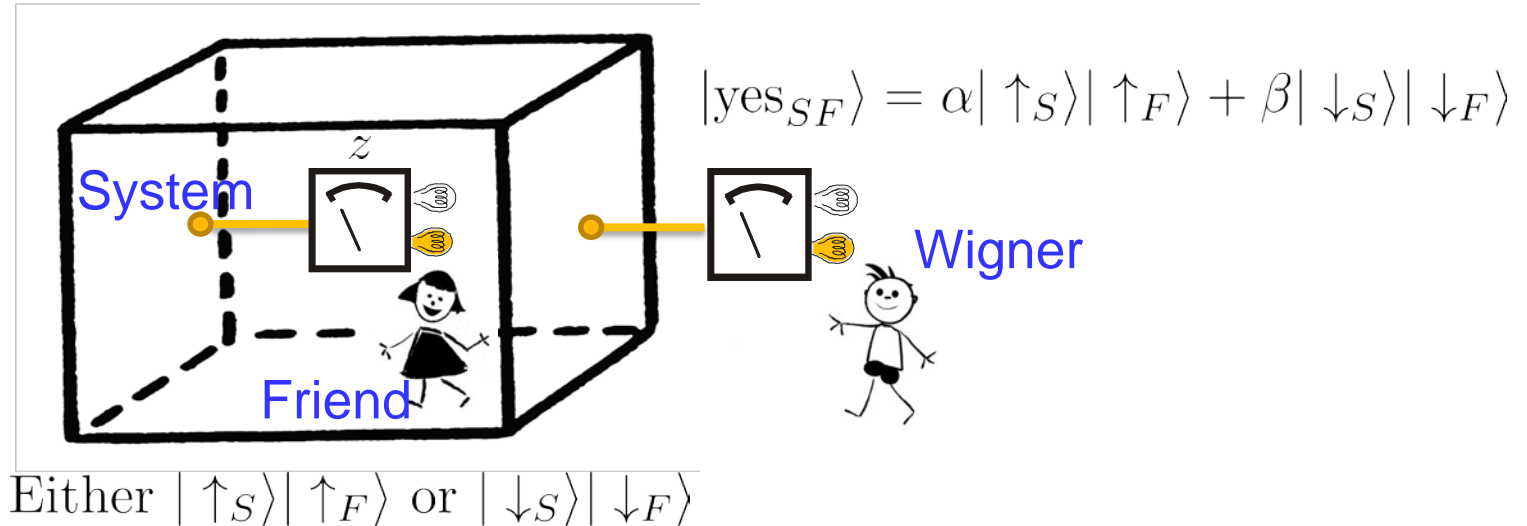
“Collapse” conditional probability

Definition:

$$P_1(n \text{ when } t_2 \mid m \text{ when } t_1) = \frac{\langle \langle \Psi \mid t_1 \rangle \langle t_1 \mid \otimes \Pi^m P^{\text{ph}}(|t_2\rangle \langle t_2| \otimes \Pi^n) P^{\text{ph}} | t_1 \rangle \langle t_1 \mid \otimes \Pi^m | \Psi \rangle \rangle}{\langle \langle \Psi \mid t_1 \rangle \langle t_1 \mid \otimes \Pi^m | \Psi \rangle \rangle}$$

- It is always a **well-defined probability**
- Correspond to **applying the “state-update rule”** after every measurement
- Reduce to the standard probability rule for non-Wigner’s friend scenarios

“Collapse” conditional probability



| $P_1(w \text{ when } t_2 \mid f \text{ when } t_1)$ | | |
|---|------------|------------|
| w | yes | no |
| f | | |
| \uparrow | α^2 | β^2 |
| \downarrow | β^2 | α^2 |

| $P_1(f \text{ when } t_1 \mid w \text{ when } t_2)$ | | |
|---|------------|------------|
| w | yes | no |
| f | | |
| \uparrow | α^2 | β^2 |
| \downarrow | β^2 | α^2 |

“Unitary” conditional probability

Definition:

$$P_1 (n \text{ when } t_2 \mid m \text{ when } t_1) = \frac{\langle \langle \Psi | (|t_2\rangle\langle t_2| \otimes \Pi^n) P^{\text{ph}}(|t_1\rangle\langle t_1| \otimes \Pi^m) | \Psi \rangle \rangle}{\langle \langle \Psi | |t_1\rangle\langle t_1| \otimes \Pi^m | \Psi \rangle \rangle}$$

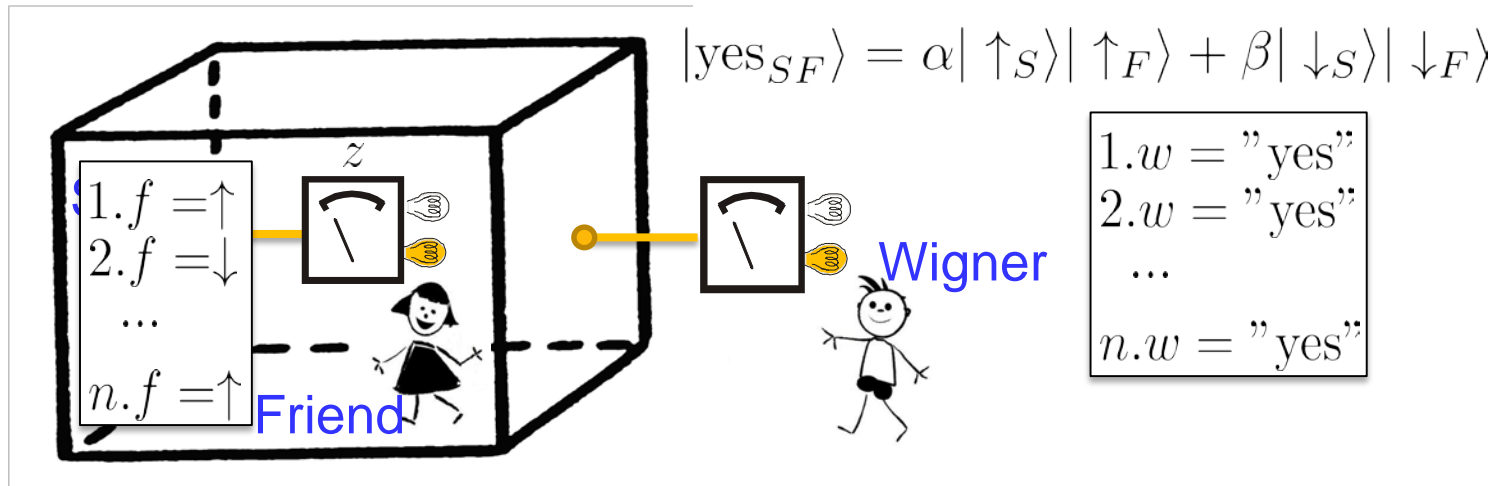
- This is a **well-defined probability only when measurement operators commute** on the physical state when compared at the same instant of time

$$[U(t_1, t_2) \Pi^m U^\dagger(t_1, t_2), \Pi^n] | \Psi \rangle \rangle = 0$$

The case of non-disturbance: $a = \alpha$ and $b = \beta$!

- Reduce to the standard probability rule for non-Wigner's friend scenarios

“Unitary” conditional probability



$$|\psi(t)_{SF}\rangle = \alpha |\uparrow_S\rangle |\uparrow_F\rangle + \beta |\downarrow_S\rangle |\downarrow_F\rangle$$

| $P_3(w \text{ when } t_2 f \text{ when } t_1)$ | | | $P_3(f \text{ when } t_1 w \text{ when } t_2)$ | | |
|--|-----|----|--|------------|----|
| $w \backslash f$ | yes | no | $w \backslash f$ | yes | no |
| \uparrow | 1 | 0 | \uparrow | α^2 | 0 |
| \downarrow | 1 | 0 | \downarrow | β^2 | 0 |

Conclusions

- Several definitions for the conditional probabilities for Wigner's friend scenarios (Page-Wootters formalism)
- All of them are equivalent for standard, non-Wigner's friend scenarios
- There are more than just the two probability rules. Is there a way of classifying all of them? What is their operational meaning? Can one reject some (all?) of them on the basis of logical inconsistencies?
- Can one construct maps between the perspectives of Wigner and his friend?

THANK YOU!